## Lecture 18

Steady-State Markov Chain

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# Steady-State

## **Steady-State Distribution**

#### Definition

For a Markov chain  $\{X_t : t \in \mathcal{T}\}$ , if a collection of limiting probabilities

$$\pi_x = \lim_{h \to \infty} P_h(x), \ x \in \mathcal{X},$$

exists, then  $\pi_x$  is called a *steady-state distribution* of the Markov chain. (Note:  $\pi$  is a distribution not the value 3.14...)

• This is the distribution of  $X_t$  after many, many transitions! (the long run probability) Muny(the long run probability)

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many

 $Ph = PoP^{(h)}$ 

## About the Steady-State Distribution

1. Obtaining the steady-state distribution:  $\pi = (\pi_1, \pi_2, \dots, \pi_n)$  is the solution to the following set of linear equations

$$\pi P = \pi, \qquad \sum_{x \in \mathcal{X}} \pi_x = 1.$$

 $(\sum_{x \in \mathcal{X}} \pi_x = 1 \text{ since each of the states should be in } \mathcal{X})$ 

- 2. What is meant by the "steady state" of a Markov chain?
  - Suppose the system has reached its steady state, so that the distribution of the states is  $P_t = \pi$ .
  - The state after one more transitions is:

 $P_{t+1} = P_t P = \pi P = \pi$ 

 Thus, if a chain is in a steady state, the distribution stays the same ("steady") after any subsequent transitions.

## Steady-State Distribution Cont.

3. The limit for  $P^h$  (the *h*-step transition matrix) is

$$\begin{array}{c} \left( \begin{array}{c} \mathbf{u} \mathbf{p} \right) \\ \mathbf{v} \\ \mathbf{v} \\ \mathbf{\Pi} \\ \mathbf{\Pi} \\ = \lim_{h \to \infty} P^{h} \\ = \begin{pmatrix} \pi_{1} & \pi_{2} & \cdots & \pi_{n} \\ \pi_{1} & \pi_{2} & \cdots & \pi_{n} \\ \vdots & \vdots & \ddots & \vdots \\ \pi_{1} & \pi_{2} & \cdots & \pi_{n} \end{pmatrix}$$

All the rows are equal and consist of the steady state probabilities  $\pi_{x}$ .

- 4. The steady-state distribution is not guaranteed to exist.
  - Steady-state distribution may or may not exist.
  - If a Markov chain is *regular*, then it has a steady state distribution. (This is what we will check).

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## Example

## Example

Example 1: Ames weather problem: Suppose the state space is  $\overline{("sunny","}$  rainy") = (1,2), with initial probability  $P_0=(
ho,1ho)$ 

• Can approximate the steady state distribution  $(\pi)$ , by 

$$P = \begin{pmatrix} 0.7 & 0.3 \\ 0.4 & 0.6 \end{pmatrix}, P^{(2)} = \begin{pmatrix} 0.61 & 0.39 \\ 0.52 & 0.48 \end{pmatrix}, P^{(3)} = \begin{pmatrix} 0.583 & 0.417 \\ 0.556 & 0.444 \end{pmatrix}$$
$$P^{(15)} \approx \ldots \approx P^{(30)} \approx \begin{pmatrix} 0.5714 & 0.4286 \\ 0.5714 & 0.4286 \end{pmatrix} = \begin{pmatrix} 4/7 & 3/7 \\ 4/7 & 3/7 \end{pmatrix} = \begin{pmatrix} \pi_1 & \pi_2 \\ \pi_1 & \pi_2 \end{pmatrix}$$

• For any given starting state distribution  $P_0 = (p, 1 - p)$ ,

$$P_0 \pi = (p, 1-p) \begin{pmatrix} 4/7 & 3/7 \\ 4/7 & 3/7 \end{pmatrix} = (4/7, 3/7)$$

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## **E**xample

• Alternatively, we can obtain steady state distribution  $(\pi)$  by

 $1. \ \pi P = \pi \longrightarrow (\Pi_1 \ \Pi_2) \begin{pmatrix} 0.7 & 0.3 \\ 0.4 & 0.6 \end{pmatrix} = (\Pi_1 \ \Pi_2)$   $2. \ \sum_{x \in \mathcal{X}} \pi_x = 1$   $0.7 \ \Pi_1 + 0.4 \ \Pi_2 = \Pi_1$   $0.3 \ \Pi_1 + 0.6 \ \Pi_2 = \Pi_2$ One equation will always reduce to be same as another equation.  $= \begin{bmatrix} 0.4 \Pi_2 = 0.3 \Pi_1 \\ 0.3 \Pi_1 = 0.4 \Pi_2 \end{bmatrix}$ Ex: If I had 3 equations here, then I'd end up with 2 unique equations, and 1 repeat  $\Rightarrow 0.4 \Pi_2 = 0.3 \Pi_1$   $\Rightarrow \Pi_2 = \frac{3}{4} \Pi_1$ Now use  $\xi \Pi_2 = 1$  to obtain values for  $\Pi_1$  &  $\Pi_2$ 6/9

Example

$$\begin{array}{l} \underbrace{z} \Pi_{\mathbf{x}} = 1 & = \overset{\mathbf{0}}{=} \Pi_{1} + \Pi_{2} = 1 \\ & \underbrace{e} \Pi_{2} = \underbrace{a}_{4} \Pi_{1} & \underbrace{e}_{4} \operatorname{Equations} \\ & \underbrace{eq_{1}}_{s} \underbrace{d}_{s} \underbrace{d}_{2} \operatorname{unFnowns} \\ & \underbrace{eq_{1}}_{s} \underbrace{d}_{s} \underbrace{d}_{1} = 1 \\ & \underbrace{eq_{1}}_{s} \underbrace{f}_{1} = \underbrace{f}_{1} = \underbrace{f}_{1} \\ & \underbrace{f}_{1} = \underbrace{f}_{1} \\ & \underbrace{eq_{1}}_{s} \underbrace{f}_{1} = \underbrace{f}_{1} \\ & \underbrace{eq_{1}}_{s} \underbrace{f}_{1} = \underbrace{f}_{1} \\ & \underbrace{eq_{1}}_{s} \underbrace{f}_{1} \\ & \underbrace{eq_{1}}_{s}$$

$$(2) \neq \Pi_z = 1$$

# Regular Markov Chain

#### Definition

A Markov Chain  $\{X_t\}$  with transition matrix P is said to be *regular* if, for some *n*, all entries of  $P^{(n)}$  are positive (> 0).

Any regular Markov chain has a steady-state distribution.

1. Not every Markov chain has a steady-state distribution. Why? Consider the following transition matrix:

$$P = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$
  
then Even Transition odd transition  
$$P^{2k} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, P^{2k-1} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \forall k \in \mathbb{N}$$
$$P^{(n)} \quad \text{will k-eep oscillating blue these two states two matrices forever:)}$$

## **Checking Regular MC**

2. As long as we find some n such that all entries of  $P^{(n)}$  are

(70) positive, then the chain is *regular*. This does not mean that a regular Markov chain has to possess this property for all n. Consider the following transition matrix,

$$P=egin{pmatrix} 0&0&1\ 2/3&0&1/3\ 1/2&1/4&1/4 \end{pmatrix},$$

then

$$P^2 = \begin{pmatrix} .500 & .250 & .250 \\ .167 & .083 & .750 \\ .292 & .063 & .646 \end{pmatrix}$$

This Markov chain is regular since  $P^{(2)}$  contains all positive elements even though the one-step transition matrix Pcontain non-positive elements.